

RADIOISOTOPE POWER SYSTEMS

An Exploration of Mission Concepts that Could Utilize Small RPS

Young H. Lee

Lead, RPS Mission Analysis
Technical Group Supervisor, Advanced Design Engineering (312D)

Alex Austin, Brian Bairstow

Jet Propulsion Laboratory, California Institute of Technology

02/27/2019

POWER TO EXPLORE

Agenda

- Mission Concept Exploration for Small RPS
 - Study Rationale, Objectives, Assumptions and Approach
 - Potential Mission Concepts
 - Mission Concepts Power, Volume and Mass Spectrum
 - Findings and Considerations
 - Study Contributors

Mission Concept Exploration for Small RPS

Rationale

- The RPS Program is interested in understanding the mission pull for small radioisotope power systems (1 mW_e - 40 W_e) in order to identify what future power system developments should be focused on.
 - » What types of missions are enabled or enhanced if there was a small RPS?
 - » What science questions could we answer?

Objectives of Study

- Explore the needs and applications for small spacecraft systems in planetary science
- Brainstorm what types of mission classes would be possible with small systems that require low average power draw
- Determine the minimum amount of power required for a deep space small mission with RPS
- Create a spectrum of potential mission ideas based on available power

Study Assumptions

RPS assumptions:

- Considered a power range of milliwatts to 10's of watts
- For this study, the type of conversion technology didn't get factored in
- Small RPS that could generate 40+ W_e are already under consideration for further development
 - » Mission concepts that require 40+ W_e didn't get considered for this study
- Considered the us of waste heat for thermal control on the spacecraft
- Made sure RPS was enabling or enhancing the mission concepts

Spacecraft systems assumptions:

- A "CubeSat" was defined as a spacecraft that can be modeled as a series of 10x10x10 cm cubes (called "U"s), each having a mass of ≤ 2 kg
 - » The largest CubeSat is a 12U, measuring 20x20x30 cm with a mass of ~24 kg
- A "SmallSat" was a spacecraft with a mass ≤ 100 kg that does not fit the CubeSat form factor
 - » Spacecraft with a mass greater than 100 kg will not be considered for this study
- Other types of small missions that require < 40 W_e was considered
 - » Example: small landers, micro-landers

Study Approach

- One day JPL Foundry's Architecture Team (A-Team) session at JPL
- Participants included:
 - Scientists
 - Instrument experts
 - Mission architects
 - CubeSat, SmallSat, small mission (i.e, small lander, micro lander) systems engineers
 - RPS experts

Study structure:

- Initial background presentation on small RPS and study goals
- A group discussion on the current status and future plans for small instruments development
- A group brainstorming session to identify types of mission classes that could be enabled or enhanced by small RPS
- Breakout groups to brainstorm and create mission architectures to populate the power spectrum using identified mission classes
- Groups reconvene to brief each other and generate a final mission classes power spectrum

Science-driven Mission Concept Identification

- Identified a list of instruments that are available now or are expected to be available in the future for small spacecraft systems, including estimates for masses and powers
- Brainstormed a list of science objectives that could be accomplished with a small RPS mission
 - Questions were organized based on targeted destinations
- Brainstormed mission classes that could be enabled or enhanced by small RPS
 - Small Landers
 - Small Rovers/Mobility Systems
 - SmallSat Swarms
 - Mother-Daughter craft

Conceptual Mission Architecture Generation

- Study participants were then split into three groups with representatives from the following areas:
 - RPS
 - Scientists
 - Mission Architects
 - Small Mission Systems Engineers
 - Instruments Engineers
- Groups worked from the identified instruments, science objectives, and mission classes to create potential mission concept architectures in more detail
- Individual groups then presented their mission concepts using a concept template to all participants

Mission Concept Template

Short description of mission concept

Science objectives: a list of science questions about the target body or observation

Mission concept sketches

RPS Requirements

- RPS power requirements
- Other requirements on the RPS
 - Volume
 - Mass
 - Thermal output
 - Packaging
 - Lifetime

Concept Summary

- A summary of the mission and flight system
- Include details on the destination

Science Instruments

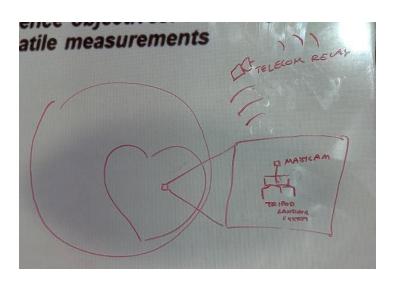
- List required instruments, including the accommodation requirements for spacecraft and RPS
- List science modes, CONOPs, and measurements taken
- Include other spacecraft requirements needed, when possible (ex. pointing)

- Required power for mission modes
- Subsystem power requirements
- Other details on power system (i.e. battery sizing)

Pluto Lander

Description: A small, long-lived lander on Pluto.

Science objectives: Ice composition, trace elements, temporal information, volatile measurements



RPS Requirements

- Power requirement: 10 W_e EOL
 - Estimated thermal output: 110 W_t
- Lifetime: 20 years
- Mass: 3-4 kg
- Volume: 6 inch diameter, 6 inch tall

Concept Summary

- Cruise to Pluto with a carrier that orbits for telecom relay (10 year cruise)
- Propulsive landing 1 km/s (20 30 kg propellant)
- · Remain on surface for ~10 years
- · Waste heat for thermal management
- Lander dry mass: 40 kg

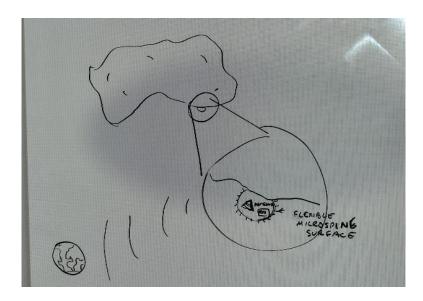
Science Instruments

- · Mast camera, GCMS, IR Spectrometer/Raman
 - Per instrument: 2-3 kg, 10 W_e active
 - · Minimal survival heating requirements
- Thermal: passive cooling system for instruments off of cold side of RPS
- CONOPS: Camera takes a picture every hour, GCMS daily measurements, IR Spectrometer every hour

- Power modes: Science -> recharge -> telecom -> recharge
 - Telecom 4 W_e transmitter
 - Science 10 W_e per measurement, 1 measurement at a time

Asteroid Beacon

A small system that attaches to asteroids and provides pings for increased tracking accuracy **Science objectives:** Origin science of the solar system, planetary defense



RPS Requirements

Power: 40 mW_e

Thermal output: 1 W_t

Could use the RHU as a heat source (rated for 10,000 g)

· Volume: 2-3 inch diameter, 4-5 inch tall

Mass: 0.8 kg

Concept Summary

- A small flight system that attaches to near Earth asteroids
- Provides pings for tracking
- A carrier spacecraft (SEP) travels to NEA and drops off small spacecraft
- · Attaches with microspine gripper
 - · No power required for attachment

Science Instruments

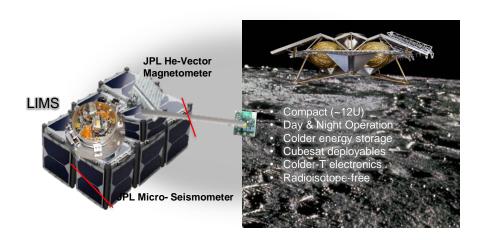
- Transmitter: 10 mW_e
 - Note: DSN can receive signals of 10⁻¹⁹ W
- Always transmitting
- Note that thermal analysis needs to be done to determine if 1 W_t can provide enough survival heat

- Carrier spacecraft has it's own power system during cruise
- Constantly transmitting pings

Lunar Geophysical Network

Network of very small packages for seismometry and magnetometry.

Science objectives: Study structure and composition of Lunar interior



Concept Summary

- ~250 kg lander package, 30 kg, 12U payload
- Deployable radiators
- Quantity: 4
- 6 year mission
- Study structure and composition of Lunar interior
- Possible need for network communication relay

Science Instruments

- Seismometer: 0.1 W_e to 1 W_e
 - Need robotic arm to deploy on lander
- Magnetometer: <1 W_e
 Deployable boom

RPS Requirements

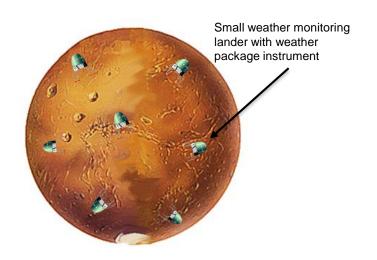
- 10 W_e end of mission required
- Other requirements on the RPS
 - Volume: < 10x20x30 centimeter (6U)
 - · Mass: 4 kg
 - Thermal output: 100 W,
 - · Packaging: integrated into payload
 - · Lifetime: 6 years

- Continuous Science Recording, no computer: 3 W_e
- Need power periodically for telecom, once daily
 - X-Band IRIS, ~35 W_e
- Need approx. 150 Wh backup Li-lon battery capacity for telecom and other systems in standby
 - Trade: RPS power vs. solar array for batteries

Long-Term Weather Monitoring; Mars

A weather monitoring package that can be deployed on Mars (Venus, Titan).

Science objectives: monitor weather and atmospheric patterns from the surface.



Concept Summary

- · Low-power weather monitoring on the surface.
- Weather package operates every 10 seconds for TBD seconds, requires 10 mW_e
- Other instruments require ~1 mW_e continuous
- Sends data back to an orbiter, twice a day 1 min each
- Life driven by RPS and instrumentation lifetime
- > 10 year mission

Science Instruments

- Temperature
- Pressure
- Wind speed
- Weather package for 10 mW_e
- Geophone
- Transmitter

RPS Requirements

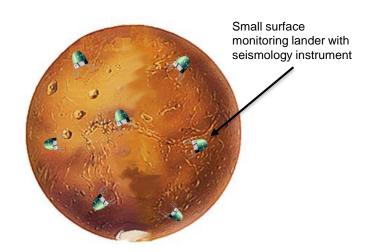
- 2 to 20 mW_e
- > 10 year mission
- Mass: TBD
- Volume: TBD

- 1 to 10 mW_e for instrumentation depending on duration of readings from weather package
- 1 W_e transmitter

Surface Monitoring; Mars

A surface monitoring package that can be deployed on Mars (Venus, Titan).

Science objectives: monitor seismic events and model interior structures from the surface.



Concept Summary

- Low-power continuous seismic monitoring on the surface.
- Sends data back to an orbiter, twice a day 1 min each
- Life driven by RPS and instrumentation lifetime
- > 10 year mission

Science Instruments

- Seismic package (50 mW_e)
 - Instrument needs to be isothermal
- Transmitter

RPS Requirements

- 100 mW_e
- > 10 year mission

Mass: TBD

Volume: TBD

- 50 mW_e for instrumentation for continuous readings from seismic package
- 1 W_e transmitter

Long-Lived Penetrator

Long-lived penetrator targeting outer planet moons, comets, asteroids, etc.

Science objectives: Geophysical assessment and temporal monitoring of distant bodies and near-surface crust characterization.



- ~80 mW_e EOM
- Other requirements on the RPS
 - Diameter < 10 cm, Length < 15 cm
 - Mass < 2 kg
 - ~3 W, thermal
 - Needs to withstand 10,000 g landing loads
 - 15 year Lifetime

Concept Summary

- Subsurface penetrator delivered by orbiter spacecraft to distant bodies (e.g. Jovian and Saturnian moons or small bodies)
- Launch 4 or more per body
- Uses RPS to perform low-power operations and charge capacitor for periodic data return
- · Requires an orbital asset to relay data

Science Instruments

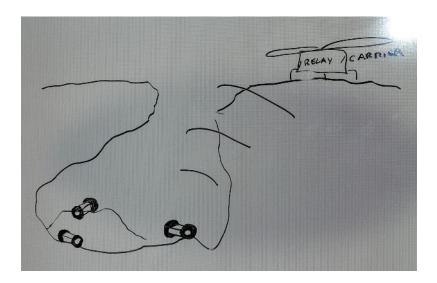
- Seismometer (0.05 W_e, 100% duty cycle)
- Dialectric Spectrometer (0.01 W_e, low duty cycle)
- Thermal Conductivity Probe (1 W_e, low duty cycle)

- Seismometer requires 50 mW_e constant.
- Supercapacitor for higher power modes
 - Telecom, spectrometer, and thermal probe operation

Mini Spelunker Rover

A small rover that is dropped into a cave/lava tube

Science objectives: Map cave interior, cave composition (reflectivity), ice mapping, temperature, pressure, relative humidity



RPS Requirements

- Power: 1 − 2 W_e
- Thermal output: 25 W_t
- Could use multiple RHU (10-25) as a heat source
- Volume: 6 inch diameter, 4 5 inch tall
- · Mass: 1 kg
 - Puffer can accommodate this mass.

Concept Summary

- Could be dropped by a helicopter or larger rover
- Wheeled mobility system
- About the size of a shoebox
- Explores the cave to map the interior with radar/lidar
- 4 x 6 x 12 in for rover
- Communication back to rover/helicopter with UHF transceiver
- Could have multiple rovers that communicate with each other

Science Instruments

- Radar/Lidar: interior mapping
 - ~100 mW_a radar
 - ~100-500 grams
- Dosimeter: radiation levels, 400 mW_e, 20 g
- Temperature, Pressure, Relative Humidity: ~ 50 mW_e,
 75 g

- Power modes:
 - Science 550 mW_e
 - Driving 1 W_a
 - Transmitting 1 W_e

Martian Deep Cave Explorer

Science objectives: Explore Martian caves and seek potential habitability



Concept Summary

- One larger rover deploys a network of 16 small rovers into the cave
 - Small rovers are powered by small RPS
- Small rovers communicate through each other to the large rover, which relays data to an orbiter
- Small rovers study and map the interior of the cave

Science Instruments

- Temperature and Pressure (1 mW_e)
- Visible near-IR camera with light source and dosimeter (1 mW_e, capacitor charge)
- Mapping Lidar (1 W_e), Penetrometer (1 mW_e)
- IR and passive NMS spectrometer (50 mW_e)
- Magnetometer (50 mW_e)

RPS Requirements

- 1.5 W_e
- · Must be magnetically clean
- · As low mass as possible for mobility
- · Volume: TBD

Mission Power Requirements

1.5 W_e

Titan Quadcopters

Titan balloon with RPS-powered quadcopters to fetch samples

Science objectives: Compositional characterization of Titan's surface, both solid and liquid, across wide geographic ranges



Concept Summary

- Deploy quadcopter "gofer" drones from constant-altitude balloon to investigate surface and return samples for analysis by instruments on balloon
- Multiple drones capable of near-continuous flight
- ~10 kg drone mass

Science Instruments

- Camera for context and surface imaging
- Sample collection device for solid and liquid surface samples

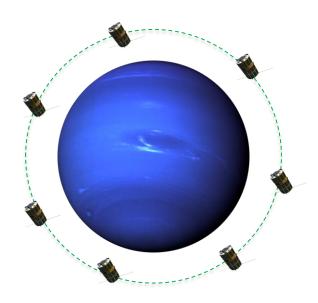
RPS Requirements

- Need ~20 W_e for unlimited mobility and science
- · Other requirements on the RPS
 - Volume: disk 30 cm diameter x 10 cm height
 - 3-5 kg
 - Needs to have thermal design compatible with operation in Titan environment
 - Lifetime 15 years (mission)

- ~15 W_e for flight
- RPS should provide all power no battery required

Magnetosphere Study Fleet

Science objectives: characterize the variation of the magnetosphere over a year. Potentially understand magnetosphere rotation for Uranus / Neptune.



Concept Summary

- 16 SmallSats deploy from a larger spacecraft to orbit the target destinations
- SmallSats are spin stabilized; no active attitude control

Science Instruments

- Magnetometer (10 mW_e)
- Electric field (10 mW_e)
- Particle analyzer (1 W_e; 10% duty cycle)
- Plasma wave spectrometer (10 mW_e)
- Telemetry to mother spacecraft (5 W_e; 20% duty cycle)
- Instruments need to be developed to meet power levels

RPS Requirements

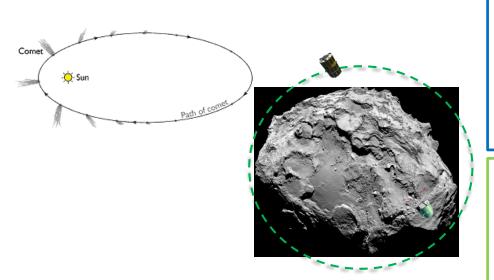
- 1.5 W_a
- 10 13 year cruise, 1 5 year orbit
- Mass: TBDVolume: TBD

- · Excluding main mothership orbiter
- ~1.4 W_e for instruments average power
- ~0.1 W_e for command data systems
 - This is challenging

Long-Period Comet Observer

Most of the time it is on the surface (far from sun); otherwise orbits.

Science objectives: long-term science study of a comet.



Concept Summary

- Long-lived (~75 year) comet observer, orbiting then package drop (or orbiter lands)
- Time-capsule concept: uses solar power when close to Sun and RPS when far from Sun
- Land a seismic package
- Monitor outgassing, comet dust, radiation environment, charging and magnetic fields, comet jets, chemical evolution
- Could have battery lifetime issues

Science Instruments

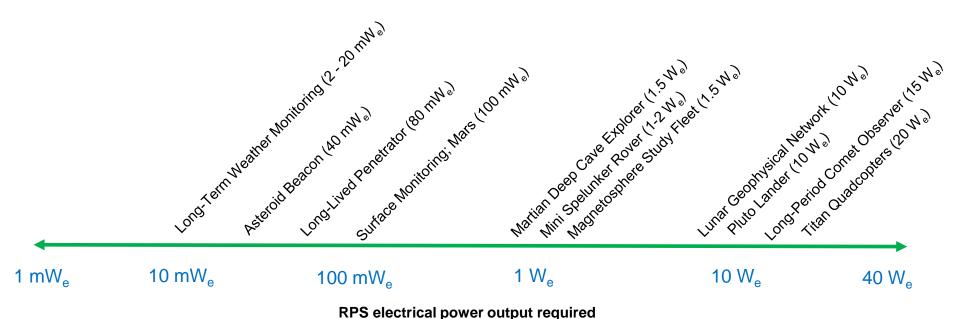
- Seismic package (1 W_e), Langmuir probe (0.5 W_e)
- GC-MS mass spec (16 W_e; 0.01 W_e average power)
- Quartz crystal microbalances (0.05 W_e)
- Visible camera (1 W_e)
- Ground penetrating radar (10 W_e; 5 min / week)
- Millimeter spec (7 W_e; 10 min / 24 hr), Dosimeter (0.05 W_e)

RPS Requirements

- 15 to 20 W_e (based on a quick ciphering of the other power requirements, should be verified)
- Use the RPS thermal output to keep flight instruments at required temperatures
- Mass: TBDVolume: TBD

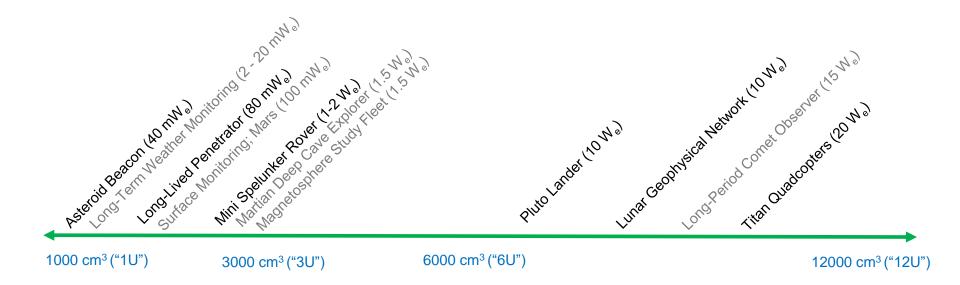
- Keep warm for instrumentation (5 W_t)
- Orbiter (4 W_e)
- Telemetry (60 Wh per week)
- Needs large batteries for trickle charging
- REP required for orbit maintenance (few watts)
- Attitude control (15 W_e) (problem, orbiter only)

Mission Concepts Power Spectrum



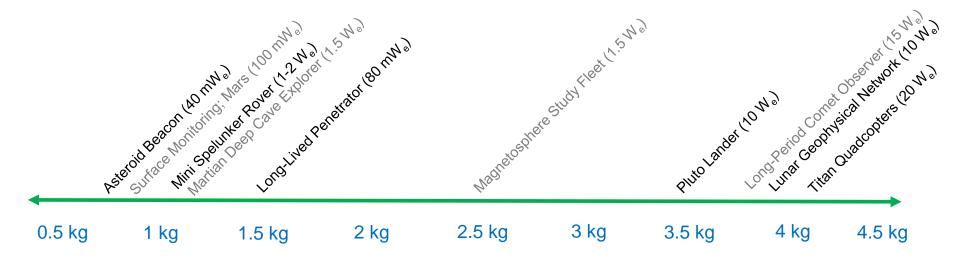
- The mission concepts are presented here in terms of required electrical power output from the RPS
- Potential mission concepts were identified across the power spectrum

Mission Concepts Size Spectrum



- The mission concepts are presented here in terms of estimated volume available for RPS
 - The RPS size estimates were based on GPHS experiences. Future RPS based on other heat sources may differ.
- Concepts in grey did not estimate a size during the study, but were estimated by the Mission Analysis team post-study

Mission Concepts Mass Spectrum



- The mission concepts are presented here in terms of estimated mass available for RPS
 - The RPS mass estimates were based on GPHS experiences. Future RPS based on other heat sources may differ.
- Concepts in grey did not estimate a mass during the study, but were estimated by the Mission Analysis team post-study

Findings

- There are a range of mission concepts that could be enabled or enhanced by small RPS with a power from 1 mW_e – 40 W_e
 - Concepts from this study were concentrated in range 2 mW_e 20 W_e
 - Prior 2004 "Enabling Exploration with Small Radioisotope Power Systems*" study mission pull findings covered 51 mission concepts (landers, rovers, sub-satellites, and deployable mini-payloads) in a similar power range from 5 mW_e 50 W_e
- These mission concepts could enable or enhance otherwise impossible mission classes with current/near-term technology
- A widely available small RPS could enable or enhance a great number of small science missions with lower cost
 - Leveraging the current rise in technology development for CubeSat/SmallSat components and instruments
- There is a strong trend amongst NASA and industry for small space missions
 - RPS can support and enhance this trend

Considerations for the RPS Program

- The RPS Program may want to consider development of a new system for small missions
 - A 1 5 W_e RPS building block may have a number of uses
 - Modularity of the system could allow for adaptability to a number of mission concepts in the 1 – 20 W_e power requirement range
- Future small RPS systems should accommodate in-situ missions and instruments
 - Many identified mission concepts were on the surface of planetary bodies
 - Some of these destinations have atmospheres that the RPS would need to operate in
- A system that fits within the CubeSat form factor could be useful, but for planetary science missions conforming to this form factor is not a top priority
 - Small satellite missions do not imply that they must be CubeSats

Study Contributors

RPS Program Office

- -Young Lee (Client Lead)
- Brian Bairstow (RPS Systems)

A-Team

- Alex Austin (Study Lead)
- Jonathan Murphy (Assistant Study Lead)
- Steve Matousek (Facilitator)
- Melissa Brown (Logistics)

Subject Matter Experts

- Jean-Pierre Fleurial (RPS Power)
- Terry Hendricks (RPS Power)
- Aaron Noell (Instruments)
- Pamela Clark (Instruments)
- Morgan Cable (Science/Instruments)
- John Elliott (Mission Architecture)
- John Brophy (Mission Architecture)
- Valentinos Constantinou (Data Science)
- Bill Smythe (Planetary Science)

- Alan Didion (SmallSat Systems Engineering)
- Macon Vining (SmallSat Systems Engineering)
- Kristina Hogstrom (SmallSat Systems Engineering)
- Colin Sheldon (SmallSat Systems Engineering - APL)
- Kalind Carpenter (Small Missions, Robots and Instruments)

Note: SMEs are from JPL unless specified

Questions?





